Constructing attribute weights from computer audit data for effective intrusion detection

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A R T I C L E   I N F O

Article history:
Received 8 December 2008
Received in revised form 26 May 2009
Accepted 23 June 2009
Available online 28 June 2009

Keywords:
Intrusion detection
Masquerade detection
Distance measures
k-Nearest neighbor
Principal component analysis
Chi-square

A B S T R A C T

Attributes construction and selection from audit data is the first and very important step for anomaly intrusion detection. In this paper, we present several cross frequency attribute weights to model user and program behaviors for anomaly intrusion detection. The frequency attribute weights include plain term frequency (TF) and various forms of term frequency-inverse document frequency (tfidf), referred to as Ltfidf, Mtfidf and LOGtfidf. Nearest Neighbor (NN) and k-NN methods with Euclidean and Cosine distance measures as well as principal component analysis (PCA) and Chi-square test method based on these frequency attribute weights are used for anomaly detection. Extensive experiments are performed based on command data from Schonlau et al. The testing results show that the LOGtfidf weight gives better detection performance compared with plain frequency and other types of weights. By using the LOGtfidf weight, the simple NN method and PCA method achieve the better masquerade detection results than the other 7 methods in the literature while the Chi-square test consistently returns the worst results. The PCA method is suitable for fast intrusion detection because of its capability of reducing data dimensionality while NN and k-NN methods are suitable for detection of a small data set because of its no need of training process. A HTTP log data set collected in a real environment and the sendmail system call data from University of New Mexico (UNM) are used as well and the results also demonstrate the effectiveness of the LOGtfidf weight for anomaly intrusion detection.

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1. Introduction

Intrusion detection is an important technique in the defense-in-depth network security framework and has become a widely studied topic in computer security in recent years (Lee and Xiang, 2001). In general, the techniques for intrusion detection are categorized as signature-based detection and anomaly detection. Anomaly detection has been an active research area because of its capability of detecting new attacks (Denning, 1987). In most computing environments, the behavior of a subject (e.g., a program, a user or a network element) is observed and analyzed via the available computer audit data (Lee and Xiang, 2001). It is always a big challenge to construct important and suitable attributes from audit data to best characterize behavioral patterns of a subject so that abnormality can be clearly distinguished from normal activities.

Most previous work in anomaly detection considered two probabilistic attributes of activities in computer systems and networks, namely, the transition attributes and the frequency attributes of audit data. One can also call these two attributes as dynamic models and static models (Yeung and Ding, 2003), or time series and non-time series (Axelsson et al., 2000). In 1996, Forrest et al. (1996) introduced an anomaly detection method called stide (sequence-time-delay embedding) by using a fixed length of system calls invoked by active and privileged processes. Profiles of normal program behavior were built by enumerating all fixed length of distinct and contiguous system calls that occur in the training data sets and unmatched sequences in actual detection are considered as anomalies. This method can be considered as using the transition attributes of audit data because each sequence contains some order information between system calls. This method is also called as n-gram. In subsequent research, a lot of work in detecting anomalous program behavior has used fixed length sequences of system calls as observable (n-gram). For example, Lee and Xiang (1998) used a data mining approach (Ripper) to study a sample of system call data and characterize sequences of normal data by a small set of rules. The sequences violating those rules were then treated as anomalies. Warrender et al. (1999) proposed a Hidden Markov Model (HMM) based method for modeling and evaluating invisible events. This method was further studied by many other research-
ers (Yeung and Ding, 2003; Cho and Park, 2003; Wang et al., 2004). Lee and Xiang (2001) used information-theoretic measures for anomaly detection. Masquerade detection is as important as anomalous program behavior detection. Masquerades are people who impersonate other people on the computer (Schonlau and Theus, 2000) and relatively difficult to be detected. Schonlau and Theus (2000) and Schonlau et al. (2001) attempted to detect masquerades by building normal user behavioral models using truncated command sequences. Experiments with six masquerade detection techniques (Schonlau and Theus, 2000; Schonlau et al., 2001): Bayes one-step Markov, Hybrid multi-step Markov, IPAM, sequence-match, compression and uniqueness, were performed and compared. The first five methods are mainly based on the transition attributes of user command data.

The frequency attributes of audit data have also been widely used for intrusion detection. Liao and Vemuri (2002) developed an intrusion detection method by using the text categorization techniques based on the frequency attributes of system calls. In subsequence research, Hu et al. (2003) applied robust support vector machines (SVM) for intrusion detection based on the frequency attributes of system call data. Zhang and Shen (2005) modified the conventional SVM, Robust SVM and one-class SVM, respectively for intrusion detection also based on the frequency property of system call data. Chen et al. (2005) developed artificial neural networks (ANNs) and SVM based methods for detecting potential system intrusions with the frequency attribute of system call data. Yeung and Ding (2003) used information measure for detecting anomalous user and program behavior based on the frequency attributes of computer audit data. In our previous work, we employed non-negative matrix factorization (NMF) (Guo et al., 2009) and self organizing maps (SOM) (Wang et al., 2006), to reduce high dimensional data for intrusion detection with high efficiency and low use of system resources. These techniques are also based on the frequency attributes of computer audit data.

In general, intrusion detection methods based on the transition information model temporal variation of the audit data. The intrusion detection methods using the frequency information, on the other hand, convert the temporal sequences into some non-temporal representation typically in the form of multidimensional feature vectors with no time dimension (Yeung and Ding, 2003). Our previous work (Wang et al., 2006, 2008) is consistent with Ye et al.’s work (2001) and indicates that considering the transition information of audit data can improve some detection accuracy but have to sacrifice some real-time performance compared to using the frequency information. In practice, audit data in intrusion detection problem is typically very large. For example, in collecting system calls of sendmail on a host machine, only 112 messages produced a combined trace with the length of over 1.5 million system calls (Forrest et al., 1996). Fast processing of massive audit data in real-time is therefore essential for a practical intrusion detection system (IDS) so that actions for response can be taken as soon as possible. However, intrusion detection methods considering the transition information of audit data usually require much time to train the models and to detect intrusions by processing a large amount of data. For example, it took Hidden Markov Models (HMM) approximately two months to train an anomaly detection model with a large data set (Warrender et al., 1999). This is clearly not adequate for real-time intrusion detection (Wang et al., 2008).

On the other hand, intrusion detection methods only taking account of frequency information usually cannot achieve good detection accuracy (Wang et al., 2006, 2008; Ye et al., 2001).

In this paper, we propose a novel intrusion detection method by constructing frequency attribute weights that not only consider the frequency information of events in each sequence of audit data, but also consider the distribution of the event in the whole data (Wang and Gombault, 2007a). We may call this kind of data preprocessing method as considering cross frequency information of audit data. The weights are originally from information retrieval and from text mining and were known as term frequency – inverse document frequency (tfidf). These weights almost do not increase the computation expense and are thus suitable for real-time detection. Plain term frequency (TF) and various types of frequency weights defined as Ltfidf, Mtlfidf and LOGtfidf are used in this paper for attribute construction. Several distance measures, namely, nearest neighbor (NN) and k-NN with Euclidean distance and with Cosine distance as well as Chi-square test are used for masquerades detection based on the four weight schemes. In this paper, we also use principal component analysis (PCA) to discover the interrelationships and dependencies among the attributes of audit data by using the covariance matrix. PCA is effective for real-time masquerade and intrusion detection due to its capacity of dimensionality reduction (Wang et al., 2008).

Extensive experiments are conducted with user command data from Schonlau and Theus (2000) and Schonlau et al. (2001) and testing results show that based on the LOGtfidf frequency weight of audit data, even simple NN method can achieve the better masquerade detection results than the other 6 methods in Schonlau and Theus (2000), Schonlau et al. (2001) and also than our previous results with NMF (Guo et al., 2009). The LOGtfidf weight improves the detection accuracy with 27.8% than plain frequency TF and improves with 30.8% than Ltfidf based on the same NN method. A real world HTTP data set and Sendmail system call data from University of New Mexico (UNM) are used as well for further validating the LOGtfidf weights and the testing results demonstrate its effectiveness for anomaly intrusion detection. The experimental results also show that PCA method improves a lot the effectiveness as well as efficiency of intrusion detection with frequency weights.

The main contributions of our work lie in the following three aspects. First, instead of using the plain frequency of audit data, we construct frequency attribute weights for masquerade and intrusion detection. The frequency weights not only consider the frequency of each event in its sequence, but also take into account of how important (or how unique) the event is to the whole data set and this helps a lot to improve the detection accuracy. The frequency weights are very effective, very simple and thus are very easy to implement onto a practical IDS. Second, we employ various distance measures (e.g., NN and k-NN method with Euclidean distance and Cosine distance) for intrusion detection and compare their detection results as well as discuss the advantages and disadvantages of these measures. Third, instead of only using the first-order statistic of audit data (e.g., Chi-square test), we use PCA to discover the relations and dependencies among attributes in audit data for intrusion detection. Also, instead of having an assumption that most audit data sets are small or low dimensional, PCA method has the capability of processing massive audit data for fast intrusion detection based on dimensionality reduction and on a simple classifier.

The remainder of this paper is organized as follows. The next section introduces the frequency attribute weights. Section 3 describes the intrusion detection methods based on various distance measures as well as the PCA method. Experiments are described and the results are summarized in Section 4. Discussion is given in Section 5. Conclusion and future work is summarized in Section 6.

2. Constructing attributes with various types of frequency weights

Attributes construction is usually the first step for anomaly detection. To facilitate comparison, we construct various types of frequency weights from audit data. The first one is the plain frequency of events in audit data and we call it as term frequency (TF). We call the second types as Liao’s term frequency – inverse...
document frequency (tfidf) as it was first used by Liao and Vemuri (2002). The other two types have never been used for intrusion detection by now and we called them as Mean tfidf (Mtfidf) and LOG tfidf (LOGtfidf), respectively. These four types of frequency attribute weights are described below and the notation and terminology used in this paper are listed in Table 1.

2.1. Plain term frequency (TF)

Plain term frequency (TF) may itself be used as the basis for attributes construction in intrusion detection. It is very straightforward. Nearly all the current frequency based intrusion detection methods used this kind of measures for attribute construction (Liao and Vemuri, 2002; Hu et al., 2003; Zhang and Shen, 2005; Chen et al., 2005; Guan et al., 2009; Wang et al., 2006, 2008; Ye et al., 2001). It is defined as

\[ tf_y = f_y \]  

(1)

2.2. Liao’s term frequency – inverse document frequency (Ltfd)

Liao and Vemuri (2002) first used this kind of measure for intrusion detection based on system call data. We then call this measure as Ltfd. In subsequent research, Zhang and Shen (2005) and Chen et al. (2005) also used the same measure for intrusion detection based on system call data. It is defined as

\[ \text{Ltfd}_y = \frac{f_y}{\sqrt{\sum_{i=1}^{m} t_{ij}^2}} \times \log \left( \frac{n}{n_i} \right) \]  

(2)

2.3. Mean term frequency – inverse document frequency (Mtfidf)

The Mtfidf has been used in information retrieval and text mining (Tang et al., 2005) and we propose to use this scheme for intrusion detection in this paper. It is defined as

\[ \text{Mtfidf}_y = f_y \times \log \left( \frac{n}{\Sigma_i} \right) \]  

(3)

2.4. LOG term frequency - inverse document frequency (LOGtfdf)

LOGtfdf is a revised scheme for attributes construction. The logarithm of the TF is to amend unfavorable linearity. It is defined as

\[ \text{LOGtfdf}_y = \log(0.5 + f_y) \times \log \left( \frac{n}{\Sigma_i} \right) \]  

(4)

3. Distance measures as well as PCA method for anomaly intrusion detection

3.1. k-Nearest neighbor (k-NN)

k-Nearest neighbor (k-NN) is a method for classifying objects based on closest training examples in the feature space. It is easily accessible but has been demonstrated effective for many classification tasks (Duda et al., 2004). For a given k, k-NN ranks the neighbors of a test sequence X among the training sample, and uses the class labels of the k most nearest neighbors to predict the class of the test vector. Euclidean distance and Cosine distance are usually used for measuring the similarity between two vectors. The Euclidean distance measure and cosine distance measure are respectively defined as follows:

\[ d_{\text{eu}}(X,T_j) = ||X - T_j|| = \sqrt{\sum_{i=1}^{m} (X_i - T_{ji})^2} \]  

(5)

\[ d_{\text{cos}}(X,T_j) = \frac{X^T T_j}{\|X\|\|T_j\|} = \frac{\sum_{i=1}^{m} X_i \times T_{ji}}{\sqrt{\sum_{i=1}^{m} X_i^2} \sqrt{\sum_{i=1}^{m} T_{ji}^2}} \]  

(6)

where \( X \) is the ith variable in the test vector \( x \) (here we use vector \( x \) to represent test sequence \( X \)); \( T_j \) is the sequence \( j \) in the training data set and \( t_{ij} \) is the ith variable in sequences \( T_j \).

In anomaly detection, each sequence of the observation data set is first transformed into a data vector, respectively based on the plain TF or various types of frequency weights defined in Eqs. (1)–(4). Suppose there are \( m \) distinct events in total in the observation data set, each sequence can then be expressed as a vector with \( m \) dimensions. The distance between a new test vector and each vector in the training data set is calculated by using Euclidean distance and Cosine distance defined in Eqs. (5) and (6). The distance scores are sorted and the k nearest neighbors are chosen to determine whether the test vector is normal or not. In anomaly detection, we average the k closest distance scores as the anomaly index. If the anomaly index of a test sequence vector is above a threshold \( \varepsilon \), the test sequence is then classified as abnormal. Otherwise it is considered as normal (Wang and Gombault, 2007a).

3.2. Nearest neighbor (NN)

Nearest neighbor (NN) is a slight modification of k-nearest neighbor (k-NN) presented in Section 3.1, when \( k = 1 \). NN is simpler than k-NN but usually is as effective as k-NN for some classification tasks. Similarly, the closest distance between a test vector \( x \) and each vector in the training set is found and used as anomaly index for anomaly detection. The test vector is classified as abnormal if its anomaly index is above a pre-defined threshold \( \varepsilon \).

3.3. Chi-square test

Chi-square distance test (also called as \( X^2 \) test) is a multivariate statistical technique. For a given test vector \( x \), the \( X^2 \) test statistic is given by the equation (Wang and Gombault, 2007b):

\[ X^2 = \sum_{i=1}^{m} \frac{(X_i - \bar{t}_i)^2}{t_i} \]  

(7)

where \( X_i \) is the ith variable in the test vector \( x \) and \( \bar{t}_i \) is the average ith variable of all the training vectors. The distance of a test vector \( x \) from the center of the normal data population can be measured by \( X^2 \) test and are considered as anomaly index for the test vector. When the \( m \) variables are independent and \( m \) is large (e.g., greater than 30), the \( X^2 \) statistic follows approximately a normal distribution according to the central limit theorem (Ye et al., 2001; Johnson and Wichern, 2002). We compute the mean and standard deviation of the \( X^2 \) population as \( X^2, \sigma_{X^2} \) and set a threshold based on a zone of some combinations of \( X^2 \) and \( \sigma_{X^2} \), e.g., \( [X^2 - 2\sigma_{X^2}, X^2 + 2\sigma_{X^2}], \) for a test vector \( x, \) if its anomaly index is outside of the zone, it is then classified as abnormal.
3.4. Principal component analysis (PCA)

Given a set of observations (sequences) be \( x_1, x_2, \ldots, x_m \), suppose each observation is represented by a row vector of length \( m \). The data set is thus represented by a matrix \( X_{n \times m} \):

\[
X_{n \times m} = \begin{bmatrix}
X_{11} & X_{12} & \cdots & X_{1m} \\
X_{21} & X_{22} & \cdots & X_{2m} \\
\vdots & \vdots & \ddots & \vdots \\
X_{n1} & X_{n2} & \cdots & X_{nm}
\end{bmatrix} = \begin{bmatrix} x_1, x_2, \ldots, x_n \end{bmatrix}
\]

The average observation is defined as

\[
\mu = \frac{1}{n} \sum_{i=1}^{n} x_i
\]

Observation deviation from the average is defined as

\[
\Phi_i = x_i - \mu
\]

The sample covariance matrix of the data set is defined as

\[
C = \frac{1}{n-1} \sum_{i=1}^{n} (x_i - \mu)(x_i - \mu)^T
\]

The covariance matrix \( C \) considers the first and second-order statistic of variables in audit data. Suppose \( (\lambda_1, u_1), (\lambda_2, u_2), \ldots, (\lambda_m, u_m) \) are \( m \) eigenvalue-eigenvector pairs of the sample covariance matrix \( C \). We choose \( k \) eigenvectors having the largest eigenvalues. Often there will be only a few large eigenvalues, and this implies that \( k \) is the inherent dimensionality of the subspace governing the "signal" while the remaining \((m-k)\) dimensions generally contain noise (Duda et al., 2004). The dimensionality of the subspace \( k \) can be determined by Duda et al. (2004)

\[
\frac{\sum_{i=1}^{k} \lambda_i}{\sum_{i=1}^{m} \lambda_i} \geq \alpha
\]

where \( \alpha \) is the ratio of variation in the subspace to the total variation in the original space. We form a \( m \times k \) matrix \( U \) whose columns consist of the \( k \) eigenvectors. The representation of the data by principal components consists of projecting the data onto the \( k \)-dimensional subspace according to the following rules (Duda et al., 2004)

\[
y_f = (x - \mu)U = \Phi_i U
\]

A test data vector \( x \) which represents a test sequence of data can be projected onto the \( k \)-dimensional subspace according to the rules defined by (13). The distance between the test data vector and its reconstruction in the subspace is simply the distance between the mean-adjusted input data vector \( \Phi = x - \mu \) and

\[
\Phi_f = (x - \mu)U^T = yU^T
\]

If the test data vector \( x \) is normal, that is, if the test data vector is very similar to the training vectors corresponding to normal behavior, the test data vector and its reconstruction will be very similar and the distance between them will be very small (Duda et al., 2004). Based on this property, normal user behavior can be profiled for masquerade and intrusion detection. As PCA seeks a projection that best represents the data in a least-square sense, we use the squared Euclidean distance to measure the distance between the two vectors (Wang and Gombault, 2007b; Wang et al., 2008):

\[
\varepsilon = \| \Phi - \Phi_f \|^2
\]

In anomaly detection, \( \varepsilon \) are characterized as anomaly indexes. If is above a predetermined threshold, the test data \( x \) is then classified as normal. Otherwise it is treated as anomalous.

4. Experiments

4.1. Masquerade detection by profiling user behavior based on command data

4.1.1. Data set

The command data sets collected by Schonlau and Theus (2000) and Schonlau et al. (2001) are used in our experiments for masquerade detection. The command data consists of user names and the associated command sequences (without arguments). Fifty users are included with 15000 consecutive commands for each user, divided into 150 blocks of 100 commands. The first 50 blocks are uncontaminated and used as training data. Starting at block 51 and onward, some masquerading command blocks, randomly drawn from outside of the 50 users, are inserted into the command sequences of the 50 users. The goal is to correctly detect the masquerading blocks in the user community. The data used in the experiments are available for downloading at http://www.schonlau.net/intrusion.html.

4.1.2. Experimental results

In the experiments, we first convert each block of data into a feature vector based on the four frequency weights. NN, k-NN with Euclidean distance and Cosine distance as well as Chi-square test and PCA are then used, respectively for masquerade detection. We use the same threshold for all the users for NN, k-NN and PCA methods and use different thresholds for different users for Chi-square distance test based on the zone defined in Section 3.3. There is no updating during the training and detection steps in our experiments. For PCA method, \( \alpha \) was set as 99.999% in the experiments based on our previous experiments (Wang et al., 2008). Receiver operating characteristic (ROC) curves are used to evaluate the masquerade detection performance based on different methods with various frequency weights. The ROC curve is the plot of detection rates (DR), calculated as the percentage of masquerades detected, against False Alarm Rates (FAR), calculated as the percentage of normal blocks falsely classified as masquerades. There is a tradeoff between the DR and FAR and the ROC curve is obtained by setting different thresholds. Points nearer to the upper left corner of the ROC curve are the most desirable, as they indicate high DR with correspondingly low FAR.

4.1.2.1. Evaluating the intrusion detection performance with different attribute weights

To evaluate the intrusion detection performance with different attribute weights, we plot ROC curves of the results shown in Fig. 1 based on NN method by using Euclidean distance measure with four weights. It is observed from the figure that LOGtfidf and Mtfdaf are much better than TF and Ltfdaf in terms of detection accuracy. In detail, LOGtfidf is slightly better than Mtfdaf and TF is better than Ltfdaf. We also plot the ROC curves based on the results of k-NN (\( k = 10 \)) with Cosine distance measure and of PCA methods by using all the four attribute weights and the results are shown in Figs. 2 and 3, respectively. It is seen that the results are consistent with those of Fig. 1.

4.1.2.2. Evaluating the intrusion detection performance with different distance measures as well as with PCA method

For comparing the detection performance with different methods, we also plot ROC curves shown in Fig. 4 by using the five distance measures as well as PCA method with LOGtfidf as it has been demonstrated as the most effective weight.

From (Fig. 4), it is observed that the PCA, NN and k-NN methods outperform Chi-square test method for masquerade detection. The Euclidean distances are slightly better than Cosine distance in terms of detection accuracy. The PCA method is comparable to
the \( k \)-NN method when \( k = 10 \). (Fig. 4) also indicates that the simple NN method with Euclidean distance measure can give a good performance for the detection, using \( \log \text{tfidf} \) attribute weight.

It is seen from Fig. 4 that the PCA method, considering the first and second-order statistic of audit data, outperforms the Chi-square test that only considers the first-order statistic of audit data. PCA method improves the detection performance with 29.3% than Chi-square test based on the same command data.

Based on the same data set, Schonlau and Theus (2000) and Schonlau et al. (2001) has used Bayes one-step Markov, Hybrid multi-step Markov, IPAM, Sequence-Match, Compression and Uniqueness for masquerade detection. We have also used NMF for masquerade detection based on the plain TF attribute of the same data (Guan et al., 2009). (Table 2) summarizes the results obtained with NN method (Euclidean distance) as well as with PCA based on the \( \log \text{tfidf} \) weight along with the results from another 7 methods reported in Schonlau and Theus (2000), Schonlau et al. (2001), and Guan et al. (2009). Fig. 5 shows the ROC curves of the results with NN method using the \( \log \text{tfidf} \) weight as well as with other 7 methods.

From (Table 2) and Fig. 5, it is observed that based on the \( \log \text{tfidf} \) weight, even the simple NN method achieves better results than the other 7 methods reported in Schonlau and Theus (2000), Schonlau et al. (2001), and Guan et al. (2009). The PCA method is comparable to NN method in terms of intrusion detection performance. By using the same NN method, the \( \log \text{tfidf} \) weight improves the detection rate with 27.9% than plain frequency TF and improves with 30.8% than \( \text{ltfidf} \) based on the same data set.

### 4.2. Anomaly detection by profiling user behavior based on HTTP log data

#### 4.2.1. Data set

Web-based attack detection is a very important issue in computer network security. To further validate the method, in this

<table>
<thead>
<tr>
<th>Method</th>
<th>False alarm (%)</th>
<th>Missing alarm (%)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Compression</td>
<td>5.0</td>
<td>65.8</td>
</tr>
<tr>
<td>Sequence-match</td>
<td>3.7</td>
<td>63.2</td>
</tr>
<tr>
<td>IPAM</td>
<td>2.7</td>
<td>58.9</td>
</tr>
<tr>
<td>Hybrid multi-step Markov</td>
<td>3.2</td>
<td>50.7</td>
</tr>
<tr>
<td>Bayes one-step Markov</td>
<td>6.7</td>
<td>30.7</td>
</tr>
<tr>
<td>Uniqueness</td>
<td>1.4</td>
<td>60.6</td>
</tr>
<tr>
<td>NMF</td>
<td>1.9</td>
<td>57.5</td>
</tr>
<tr>
<td>NN with ( \log \text{tfidf} ) ( \epsilon = 1.38 )</td>
<td><strong>1.3</strong></td>
<td><strong>57.5</strong></td>
</tr>
<tr>
<td>NN with ( \text{tf} ) ( \epsilon = 0.60 )</td>
<td>1.3</td>
<td>79.7</td>
</tr>
<tr>
<td>NN with ( \text{ltfidf} ) ( \epsilon = 1.88 )</td>
<td>1.3</td>
<td>83.1</td>
</tr>
<tr>
<td>PCA with ( \log \text{tfidf} ) ( \epsilon = 1.81 )</td>
<td><strong>1.1</strong></td>
<td><strong>57.5</strong></td>
</tr>
<tr>
<td>PCA with ( \text{tf} ) ( \epsilon = 0.18 )</td>
<td>1.1</td>
<td>75.3</td>
</tr>
</tbody>
</table>
paper, we also used a real world HTTP log data set to evaluate the performance of LOGtfidf and plain frequency with NN classifier. The HTTP log data was collected on a HTTP server (Apache). In order to reduce a large amount of noise contained in the data set, we filtered out nearly all the static requests (e.g., .html, .jpg, .wav, .wmv, .pdf, .swf) as well as most widely known search engine robots (e.g., googlebot, Msnbot, Spider) before the detection, because static requests cannot be attacks to the server. The data we used in the experiments includes 33967 HTTP requests in which 33856 requests are normal and 111 requests are attacks.

In the experiments, we use character distribution of each path source in each HTTP request as the features. There are 256 types of ASCII codes in total and only 95 types of ASCII codes appear in the path source. These ASCII codes are between 33 and 127. The LOGtfidf weights as well as the plain frequency of each ASCII code in each path source are computed. In this way, each HTTP request is thus represented by a 95-dimensional vector and our goal is to identify whether each vector is normal or anomalous.

4.2.2. Experiment results

We used the first normal 800 HTTP requests for training and used all the other data for test. The comparison results with NN method are shown in Table 3 and the ROC curves are presented in Fig. 6.

From (Table 3) and Fig. 6, it is observed that even using the NN method, LOGtfidf improves the detection accuracy comparing to using plain TF.

Table 3

<table>
<thead>
<tr>
<th>LOGtfidf</th>
<th>TF</th>
</tr>
</thead>
<tbody>
<tr>
<td>Detection rate (%)</td>
<td>False alarm rate (%)</td>
</tr>
<tr>
<td>21.6</td>
<td>0.2</td>
</tr>
<tr>
<td>26.1</td>
<td>0.3</td>
</tr>
<tr>
<td>63.1</td>
<td>1.7</td>
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<td>85.6</td>
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<tr>
<td>95.5</td>
<td>3.7</td>
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<tr>
<td>100</td>
<td>4.6</td>
</tr>
</tbody>
</table>

4.3. Anomaly detection by profiling program behavior based on system call data

4.3.1. Data set

We used another data set to test the robustness of the LOGtfidf weight with NN. The data set is sendmail system call sequences, collected in a UNIX-based host at UNM by Forrest et al. (1996), since they were widely used for testing many other intrusion detection models. In the experiments, we used CERT synthetic sendmail data in which one sequence of normal data named “sendmail.int.gz” and 12 sequences of abnormal data including 4 syslog attacks and 2 unsuccessful intrusions (sm5x and sm565a) are used for test. The data sets are available at http://www.cs.unm.edu/immsec/, and the procedures of generating the data are also described on the website.

4.3.2. Experiment results

There are 147 normal traces and 34 abnormal traces of system calls in total in the data set. Each trace of the data corresponds a single process. In the experiments, all the system calls associated to the same process is grouped together. We then used LOGtfidf weight to convert each process into a vector. Intrusion detection is to identify whether a vector is normal or anomalous. Twenty normal processes are randomly selected for training and the other
of circumstances) is expected for a practical IDS. In real environments, however, false alarm rate with 1% normally can be considered as a good level for the detection. In anomaly intrusion detection, besides the features and statistical detection methods, the question of what kind of data source is used is also crucial. Although the detection results on command data is not very good, in the experiments on system call data, all the attacks are detected without any false alarms, using the frequency weights. In intrusion detection, we suggest that cross frequency weights should be tried, at least to see the comparison results with plain frequency. As shown in our experiments, frequency weights improve the detection rates in many computing circumstances.

In this paper, we use principal component analysis (PCA) to discover the interrelationships and dependencies among the attributes of audit data for intrusion detection. The testing results show that PCA, considering the first and second-order statistic of audit data, is better than Chi-square test method that only takes into account the first-order statistic of audit data for intrusion detection.

Based on LOGtfidf weight, k-NN and PCA are both effective and comparable for intrusion detection. k-NN is a simple algorithm and easily accessible. Compared to PCA, k-NN method doesn’t need training process. However, it requires $O(mnq)$ calculations during test step, where $m$ is the dimensionality of the vector and $n$ is the total number of training samples. Usually if the dimensionality of the data is very high and the training data set is very large, it needs a lot of computation. PCA, on the other hand, is relatively time consuming during training process, but only requires $O(mq)$ calculations in detection process, where $q$ is the number of principal components used in the model. Experimental results show that after the high dimensional data is reduced, the original data can be represented by a linear combination of only a small number of principle components without sacrificing valuable information. Based on PCA, normally the original data can be largely reduced for intrusion detection and $q$ is very small. Because the subspace is low dimensional and the classifier is simple, little computational effort is required for the detection. Moreover, system resources may be largely saved for low dimensional data which are conveniently stored and transmitted. It is suggested that PCA is more suitable for processing large of amount of network data for anomaly intrusion detection. However, as a very simple method, k-NN is appropriate for intrusion detection if the data is not so massive, because it is light-weight to periodically retrain the detection model by only collecting normal data.

6. Conclusion

In this paper, we proposed plain TF weight and several cross frequency weights, namely, LOGtfidf, Mtfidf and Ltfidf for feature construction from audit data. The nearest neighbor (NN) and k-NN with Euclidean distance and Cosine distance as well as PCA and Chi-square test are employed for anomaly intrusion detection. Command data from Schonlau and Theus (2000) and Schonlau et al. (2001) are used to validate the various weights and the different intrusion detection methods. Experimental results show that the LOGtfidf and Mtfidf weight are better than plain term frequency (TF) and Ltfidf in terms of detection accuracy. For detection algorithms, PCA and k-NN are effective and comparable for intrusion detection while Chi-square test consistently returns the worst results. Based on the LOGtfidf weight, even the simple NN method can achieve the better results than the other 7 methods in Schonlau and Theus (2000), Schonlau et al. (2001) and in Guan et al. (2009). The LOGtfidf weight improves the detection rates with 27.9% than plain TF and improves with 30.8% than Ltfidf based on the NN method. A real world HTTP log data set and the sendmail
system call data from UNM are used as well in the experiments and the testing results also demonstrated the effectiveness of LOGtfidf weight for anomaly intrusion detection.

Research in progress is on finding more effective weights for constructing valuable attributes from audit data to improve the detection performance. The ways how to combine the frequency attributes with the transition information of audit data to achieve lower false alarm rates and missing alarm rates are also being investigated. Masquerade detection is a difficult task. We also plan to resolve this issue by using other data sources, e.g., key stoke behaviors or adding some arguments to the truncated commands.

Acknowledgements

The authors thank Dr. Florent Masseglia, INRIA Sophia Antipolis, France, for his help to provide a real world HTTP log data set. The work of NTNU part was supported by the Centre for Quantifiable Quality of Service in Communication Systems (Q2S), Centre of Excellence, which is appointed by the Research Council of Norway and funded by the Research Council, NTNU and UNINETT. The work of TELECOM Bretagne part was supported by French Ministry of Research (CNRS ACI-SI), Dependable Anomaly Detection with Diagnosis (DADDi) project. The research of the first author is also supported by ERCIM “Alain Bensousan” Fellowship Programme.

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